## A perfectly secure symmetric encryption scheme: ONE-TIME PAD

This encryption scheme achieves information-theoric security.

**Definition 1** (Symmetric encryption). Let  $\mathcal{K}$  be a key space,  $\mathcal{P}$  be a plain-text space and let  $\mathcal{C}$  be a ciphertext space These three spaces are finite spaces.

A symmetric encryption scheme over  $(\mathcal{K}, \mathcal{P}, \mathcal{C})$  is a tuple of three algorithms (KeyGen, Enc, Dec) :

 $\triangleright$  KeyGen provides a sample k of  $\mathcal{K}$ ;

 $\triangleright \operatorname{Enc}: \mathcal{K} \times \mathcal{P} \to \mathcal{C};$ 

 $\triangleright \operatorname{Dec}: \mathcal{K} \times \mathscr{C} \to \mathscr{P}.$ 

Without loss of generality, we will assume that im Enc =  $\mathscr{C}$ . We want to ensure **Correctness**: for any key  $k \in \mathscr{K}$  and message  $m \in \mathscr{P}$ , we have that:

$$Dec(k, Enc(k, m)) = m.$$

The elements m and k are independent random variables and all the elements in  $\mathcal{K}$  and  $\mathcal{P}$  have non-zero probability.

**Remark 1.** The algorithm Enc could (and should<sup>1</sup>) be probabilistic. However, the algorithm Dec is deterministic.

So far, we did not talk about efficiency of these algorithms.

**Definition 2** (Shannon, 1949). A symmetric encryption scheme is said to have *perfect security* whenever, for any  $\bar{m}$  and any  $\bar{c}$ ,

$$\Pr_{k,m}[m = \bar{m} \mid \operatorname{Enc}_k(m) = \bar{c}] = \Pr_m[m = \bar{m}].$$

The intuition is that knowing the encrypted message tells me *nothing* about the message.

**Lemma 1** (Shannon). Given a symmetric encryption scheme (KeyGen, Enc, Dec) has perfect security then  $|\mathcal{K}| \ge |\mathcal{P}|$ .

**Proof.** Let  $\bar{c} \in \mathscr{C}$  and define

$$\mathcal{S} := \{ \bar{m} \in \mathcal{P} \mid \exists \bar{k} \in \mathcal{K}, \bar{m} = \mathrm{Dec}(\bar{k}, \bar{c}) \}.$$

Let  $N := |\mathcal{S}|$ . We have that  $N \leq |\mathcal{H}|$  as Dec is deterministic. We also have that  $N \leq |\mathcal{P}|$  as  $\mathcal{S} \subseteq \mathcal{P}$ . Finally, assume  $N < |\mathcal{P}|$ . This means, there exists  $\bar{m} \in \mathcal{P}$  such that  $\bar{m} \notin \mathcal{S}$ . Then,

$$\Pr[m = \bar{m} \mid \operatorname{Enc}_k(m) = \bar{c}] = 0,$$

but by assumption,  $\Pr[m=\bar{m}] \neq 0$ . So this is not a perfectly secure scheme. We can conclude that

$$N = |\mathcal{P}| \le |\mathcal{K}|.$$

<sup>1</sup>If the algorithm is deterministic, if we see two identical ciphers we know that the messages are identical, and this can be seen as a vulnerability of this protocol.

**Example 1** (One-Time PAD). Let  $\mathcal{K} = \mathcal{C} = \mathcal{P} = \{0,1\}^{\ell}$ . Here are the algorithms used:

- $\triangleright$  KeyGen samples from  $\mathcal{U}(\{0,1\}^{\ell})$ .
- $\triangleright$  Enc(k, m) we compute the XOR  $c = m \oplus k$ .
- $\triangleright$  Dec(k, m) we compute the XOR  $m = c \oplus k$ .

**Theorem 1.** The One-Time PAD is a perfectly-secure symmetric encryption.

**Proof. Correctness.** We have that

$$Dec(k, Enc(k, m)) = k \oplus k \oplus m = m.$$

**Security.** We have, by independence of m and k we have that

$$\Pr[m = \bar{m} \mid \operatorname{Enc}(k, m) = \bar{c}] = \Pr[m = \bar{m} \mid k \oplus m = \bar{c}]$$
$$= \Pr[m = \bar{m}].$$

**Remark 2.** This example is not practical:

- ▶ keys need to be larger than the message;
- $\triangleright$  you cannot encrypt twice: for example,  $c_1 = m_1 \oplus k$  and  $c_2 = m_2 \oplus k$ , then we have  $c_1 \oplus c_2 = m_1 \oplus m_2$ .

This last part is why that protocol is called a *One-Time secure* encryption.

We want to be able to encrypt arbitrarily long messages! We will have to make a trade-off and we choose to not care about *perfect* security. Why? In real life, we don't care about proving that something is proven to be absolutely infeasible, we only want to believe it is

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infeasible in practice.

## Computational complexity is sufficient in practice.

Let us be more precise.

**Definition 3.** Let  $\mathfrak{D}_0$  and  $\mathfrak{D}_1$  be two distributions over  $\{0,1\}^n$ .

An algorithm  $\mathcal{A}: \{0,1\}^n \to \{0,1\}$  is called a distinguisher between  $\mathfrak{D}_0$  and  $\mathfrak{D}_1$ . We define its distinguishing advantage as:

$$\mathrm{Adv}_{\mathscr{A}} := \Big|\underbrace{\Pr_{\substack{x \leftarrow \mathfrak{D}_1}} [\mathscr{A}(X) = 1]}_{\text{probability of being right}} - \underbrace{\Pr_{\substack{x \leftarrow \mathfrak{D}_0}} [\mathscr{A}(X) = 1]}_{\text{probability of being mistaken}} \Big|.$$

We say that  $\mathfrak{D}_0$  and  $\mathfrak{D}_1$  are computationally indistinguishable if for any efficient distinguisher  $\mathcal{A}$  its advantage  $\operatorname{Adv}_{\mathcal{A}}$  is small.

This definition is not very formal yet, we have not defined "efficient" and "small." This can be formalized by introducing a parameter  $\lambda \in \mathbb{N}$  called the *security parameter*.

**Definition 4.** Let  $(\mathfrak{D}_{0,\lambda})_{\lambda\in\mathbb{N}}$  and  $(\mathfrak{D}_{1,\lambda})_{\lambda\in\mathbb{N}}$  be two distributions over  $\{0,1\}^{n(\lambda)}$  for a non-decreasing polynomial  $n(\lambda)$ . The value of  $\lambda\in\mathbb{N}$  is called the *security parameter*.

An algorithm  $\mathcal{A}: \{0,1\}^{n(\lambda)} \to \{0,1\}$  is called a *distinguisher* between the distributions  $\mathfrak{D}_{0,\lambda}$  and  $\mathfrak{D}_{1,\lambda}$ . We define its *distinguishing* advantage as:

$$\mathrm{Adv}_{\mathscr{A}}(\lambda) := \Big|\underbrace{\Pr_{x \leftarrow \mathfrak{D}_{1,\lambda}}[\mathscr{A}(X) = 1]}_{\text{probability of being right}} - \underbrace{\Pr_{x \leftarrow \mathfrak{D}_{0,\lambda}}[\mathscr{A}(X) = 1]}_{\text{probability of being mistaken}}\Big|.$$

We say that  $\mathfrak{D}_{0,\lambda}$  and  $\mathfrak{D}_{1,\lambda}$  are computationally indistinguishable if for any distinguisher  $\mathscr{A}$  running in  $O(\lambda^c)$  for some  $c > 0^2$  its advantage  $Adv_{\mathscr{A}}$  is a  $o(1/\lambda^c)$  for some c > 0.

Our goal now is to extend the One-Time PAD to messages m larger than the key k. We want to construct some function G that takes as input the key  $k \in \{0,1\}^n$  and expend it to a string  $G(k) \in \{0,1\}^\ell$  for some  $\ell > k$  that is computationally hard to distinguish from a uniform random string. This is called a PGR or pseudo-random generator.

**Definition 5.** A pseudo-random generator is a pair of poly-time algorithms (Setup, G) such that:

- $\triangleright$  Setup is an algorithm that takes as input a security parameter  $\lambda$  (taken as a string  $1^{\lambda}$  of length  $\lambda$ , *i.e.* we write  $\lambda$  in unary) and returns a public parameter;

## such that

- $\triangleright$  G is deterministic;
- $\triangleright \ \ell(\lambda) > n(\lambda)$  (we say that it is expanding)
- by the distributions  $\{\mathcal{U}(\{0,1\}^{\ell(\lambda)})\}_{\lambda\in\mathbb{N}}$  and  $\{G(\mathcal{U}(\{0,1\}^{n(\lambda)}))\}_{\lambda\in\mathbb{N}}$  are computationally indistinguishable (we call it *pseudo-randomness*).

Another way of defining a pseudo-random generator is with unpredictability instead of pseudo-randomness.

**Definition 6.** This is the same definition as before but replacing pseudo-randomness with *unpredictability*.

A PRG (Setup, G) is unpredictable if, for any index  $i \in \{0, \dots, \ell(\lambda)\}$ 

<sup>&</sup>lt;sup>2</sup>This means it is polynomial in  $\lambda$ , which we will write poly( $\lambda$ )

<sup>&</sup>lt;sup>3</sup>This means it is negligible in terms of  $\lambda$ , which we will write negl( $\lambda$ ).

and any efficient adversary  $\mathcal{A}: \{0,1\}^n \to \{0,1\}$ , we have that:

$$\left| \Pr_{k \leftarrow \mathcal{U}(\{0,1\}^{n(\lambda)}} \left[ \mathcal{A}(G(k)_{|i}) = G(k)_{i+1} \right] - \frac{1}{2} \right| = \operatorname{negl}(\lambda).$$

We can now prove that the two definitions are equivalent.

## **Theorem 2.** The two definitions of a PRG are equivalent.

**Proof.** To simplify, we will remove the security parameter from the notations.

On one side, assume we have a predictor  $\mathcal{A}: \{0,1\}^i \to \{0,1\}$  that succeeds in guessing  $G(k)_{i+1}$  with non-negligible probability. We then construct a distinguisher  $\mathfrak{B}$  against pseudo-randomness as  $\mathfrak{B}$  receive a sample x from either  $\mathfrak{D}_0 = \mathcal{U}(\{0,1\}^\ell)$  or  $\mathfrak{D}_1 = G(\mathcal{U}(\{0,1\}^n))$ : algorithm  $\mathfrak{B}$  runs  $\mathfrak{A}$  on input  $x_{|i}$  and checks if  $\mathcal{A}(x_{|i}) \stackrel{?}{=} x_{i+1}$ . In that case,  $\mathfrak{B}$  will return 1; otherwise it returns 0. What is the advantage of  $\mathfrak{B}$ ?

$$\operatorname{Adv}_{\mathfrak{B}} = \Big| \Pr_{x \leftarrow \mathfrak{D}_{1}} [\mathfrak{B}(x) = 1] - \underbrace{\Pr_{x \leftarrow \mathfrak{D}_{0}} [\mathfrak{B}(x) = 1]}_{1/2} \Big|$$
$$= \Big| \Pr_{x \leftarrow \mathfrak{D}_{1}} [\mathfrak{A}(x_{|i}) = x_{i+1}] - \frac{1}{2} \Big|.$$

This is the definition of the predictability advantage of  $\mathcal{A}$  (which is non-negligible by assumption).

Next, we will use a technique called an *Hybrid Argument* (due to Yao in '82). Assume we have a distinguisher  $\mathcal{A}$  such that

$$Adv_{\mathscr{A}} = \Big| \Pr_{x \leftarrow \mathscr{D}_{1}} [\mathscr{A}(x) = 1] - \Pr_{x \leftarrow \mathscr{D}_{0}} [A(x) = 1] \Big|$$

is non-negligible, say  $\mathrm{Adv}_{\mathscr{A}} \geq \varepsilon$ . We then define  $\ell+1$  distributions

 $(\mathfrak{D}_i)_{i=0,...,\ell}$  as

$$\mathfrak{D}_{i} := \left\{ x \in \{0,1\}^{\ell} \middle| \begin{array}{c} x_{|i} = G(k)_{|i} \text{ for } k \leftarrow \mathcal{U}(\{0,1\}^{n}) \\ x_{|i+1,\dots,\ell} \leftarrow \mathcal{U}(\{0,1\}^{\ell-i}) \end{array} \right\}.$$

We then have, by all the terms cancelling (this is a telescoping sum), that:

$$\varepsilon \leq \operatorname{Adv}_{\mathscr{A}}(\mathfrak{D}_{0}, \mathfrak{D}_{n}) = \left| \sum_{i=0}^{\ell} \left( \Pr_{x \leftarrow \mathfrak{D}_{i+1}} [\mathscr{A}(x) = 1] - \Pr_{x \leftarrow \mathfrak{D}_{i}} [\mathscr{A}(x) = 1] \right) \right|$$

$$\leq \sum_{i=0}^{\ell} \left| \Pr_{x \leftarrow \mathfrak{D}_{i+1}} [\mathscr{A}(x) = 1] - \Pr_{x \leftarrow \mathfrak{D}_{i}} [\mathscr{A}(x) = 1] \right|$$

$$\leq \sum_{i=0}^{\ell} \operatorname{Adv}_{\mathscr{A}}(\mathfrak{D}_{i}, \mathfrak{D}_{i+1}).$$

By the pigeonhole principle, we have that there exists an  $i \in \{0, \dots, \ell\}$ , such that

$$\Big|\Pr_{x \leftarrow \mathfrak{D}_{i+1}}[\mathfrak{A}(x) = 1] - \Pr_{x \leftarrow \mathfrak{D}_i}[\mathfrak{A}(x) = 1]\Big| \ge \frac{\varepsilon}{\ell + 1}.$$

As  $\varepsilon$  is non-negligible and  $\ell+1$  being polynomial in  $\lambda$ , we have that  $\varepsilon/(\ell+1)$  is non-negligible. How to turn this into a predictor for i? Let us define  $\mathfrak{B}_i$  as a predictor which is given  $G(k)_{|i|}$  and supposed to predict  $G(k)_{i+1}$ . Algorithm  $\mathfrak{B}_i$  will computes  $x \in \{0,1\}^{\ell}$  with  $x \leftarrow G(k)_{|i|} || y$  where  $y \leftarrow \mathcal{U}(\{0,1\}^{\ell-i})$ . Then  $\mathfrak{B}_i$  runs algorithms  $\mathfrak{A}$  on input x, and  $\mathfrak{A}$  returns a bit  $b \in \{0,1\}$  and  $\mathfrak{B}_i$  outputs a prediction  $x_{i+1}$  for  $G(k)_{i+1}$  if b=1 and  $1-x_{i+1}$ 

otherwise. What is the prediction advantage of  $\mathfrak{B}_i$ ?

$$\Pr[\mathfrak{B}_{i}(G(k)_{|i}) = G(k)_{i+1}]$$

$$= \Pr\begin{bmatrix} \mathfrak{A}(x) = 0 \land x_{i+1} = 1 - G(k)_{i+1} \\ \lor \\ \mathfrak{A}(x) = 1 \land x_{i+1} = G(k)_{i+1} \end{bmatrix}$$

$$= \Pr_{x \leftarrow \mathfrak{D}_{i}}[\mathfrak{A}(x) = 0 \land x_{i+1} = 1 - G(k)_{i+1}]$$

$$+ \Pr_{x \leftarrow \mathfrak{D}_{i}}[\mathfrak{A}(x) = 1 \land x_{i+1} = G(k)_{i+1}]$$

$$= \frac{1}{2} \Pr_{x \leftarrow \bar{\mathfrak{D}}_{i+1}}[\mathfrak{A}(x) = 0] + \frac{1}{2} \Pr_{x \leftarrow \bar{\mathfrak{D}}_{i}}[\mathfrak{A}(x) = 1]$$

$$= \frac{1}{2} \left( \Pr_{x \leftarrow \bar{\mathfrak{D}}_{i+1}}[\mathfrak{A}(x) = 1] + 1 - \Pr_{x \leftarrow \bar{\mathfrak{D}}_{i+1}}[\mathfrak{A}(x) = 1] \right)$$

where we write  $\bar{\mathfrak{D}}_{i+1}$  is the "flipped" of  $\mathfrak{D}_{i+1}$ . We have that:

$$\Pr_{x \leftarrow \mathfrak{D}_{i}}[\mathcal{A}(x) = 1]$$

$$= \Pr_{x \leftarrow \mathfrak{D}_{i}}[\mathcal{A}(x) = 1 \land x_{i+1} = G(k)_{i+1}]$$

$$+ \Pr_{x \leftarrow \mathfrak{D}_{i}}[\mathcal{A}(x) = 1 \land x_{i+1} = 1 - G(k)_{i+1}]$$

$$= \frac{1}{2} \Big( \Pr_{x \leftarrow \mathfrak{D}_{i}}[\mathcal{A}(x) = 1] + \Pr_{x \leftarrow \mathfrak{D}_{i+1}}[\mathcal{A}(x) = 1] \Big),$$

thus

$$\Pr_{x \leftarrow \bar{\mathcal{D}}_{i+1}}[\mathcal{A}(x) = 1] = 2 \Pr_{x \leftarrow \mathcal{D}_i}[\mathcal{A}(x) = 1] - \Pr_{x \leftarrow \mathcal{D}_{i+1}}[\mathcal{A}(x) = 1].$$

Hence,

$$\begin{split} \Pr[\mathcal{B}_i(G(k)_{|i}) - G(k)_{i+1}] &= \\ \frac{1}{2} \Pr_{x \leftarrow \mathcal{D}_{i+1}}[\mathcal{A}(x) = 1] + 1 - 2 \Pr_{x \leftarrow \mathcal{D}_i}[\mathcal{A}(x) = 1] + \Pr_{x \leftarrow \mathcal{D}_{i+1}}[\mathcal{A}(x) = 1]. \end{split}$$

Finally, we can conclude that:

$$\operatorname{Adv}_{\mathscr{A}}(\mathfrak{D}_{i},\mathfrak{D}_{i+1}) = \left| \Pr[\mathfrak{B}_{i}(G(k)_{|i}) = G(k)_{i+1}] - \frac{1}{2} \right| \ge \frac{\varepsilon}{n}.$$